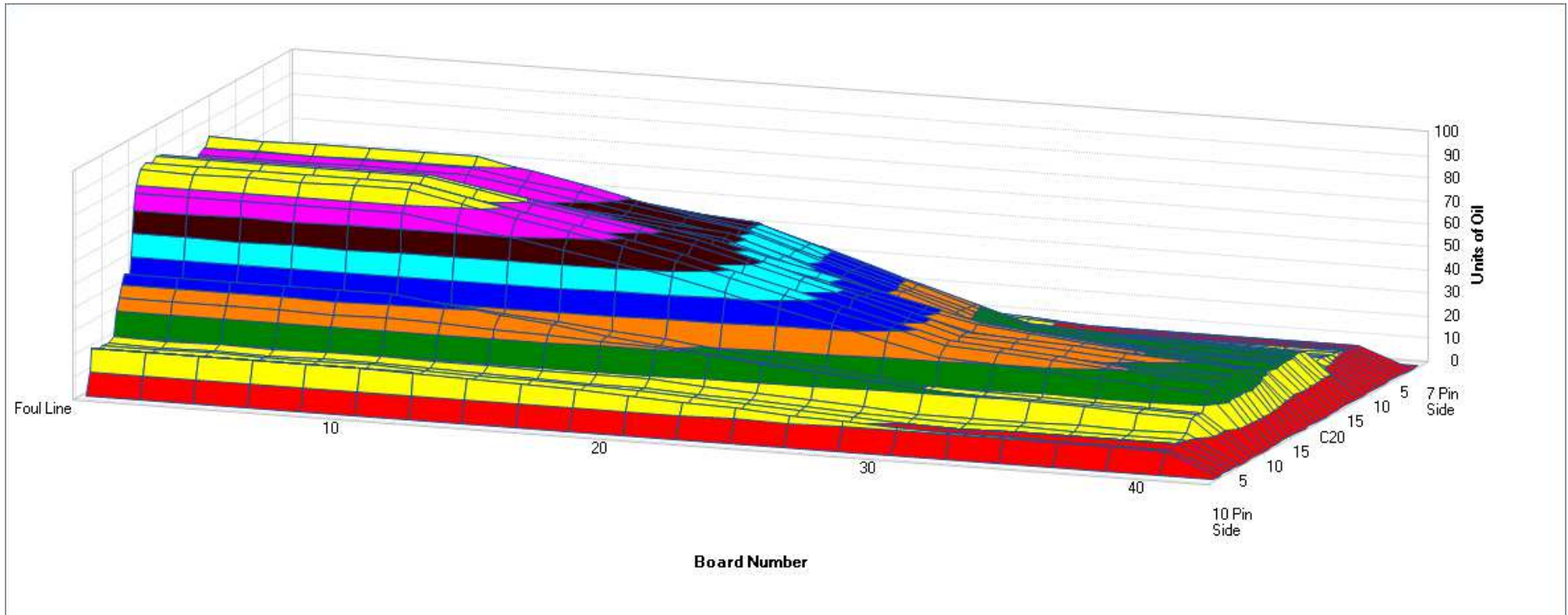


Tentative

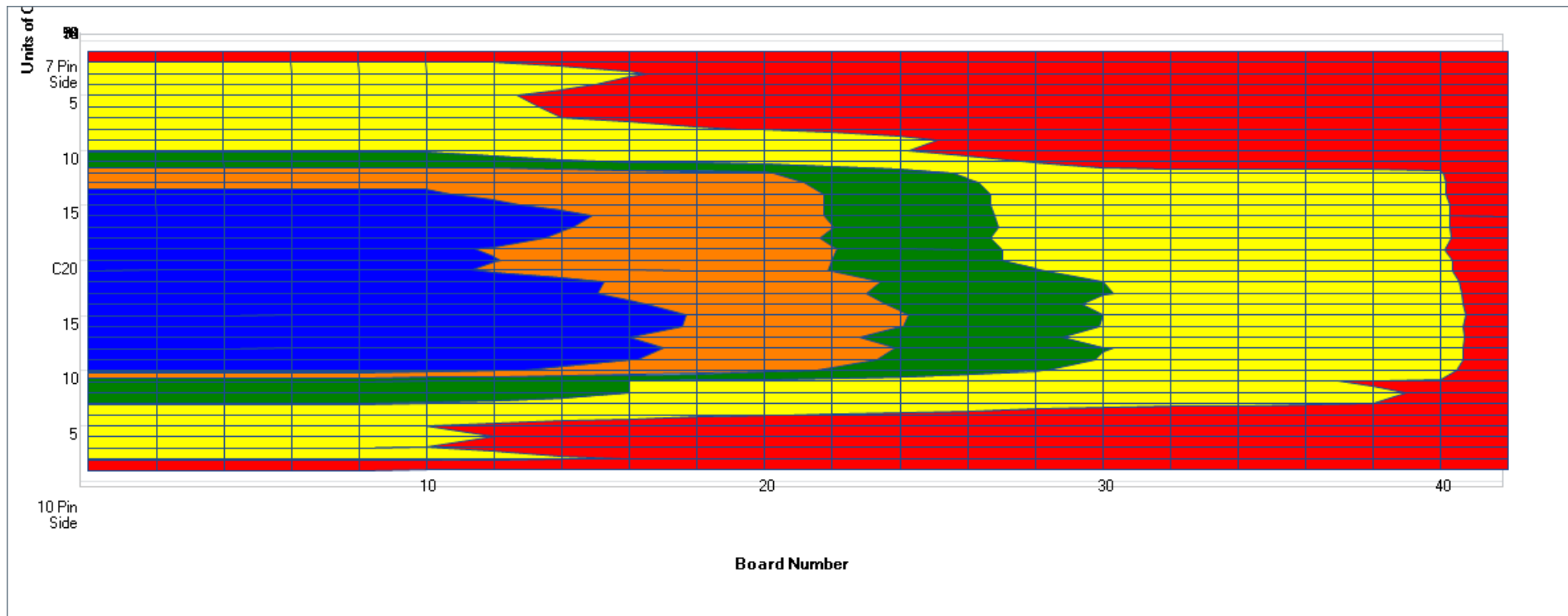


FormulaACC

HVO **SUMMIT**

Utopia
LANE
LUBRICANT

Tentative

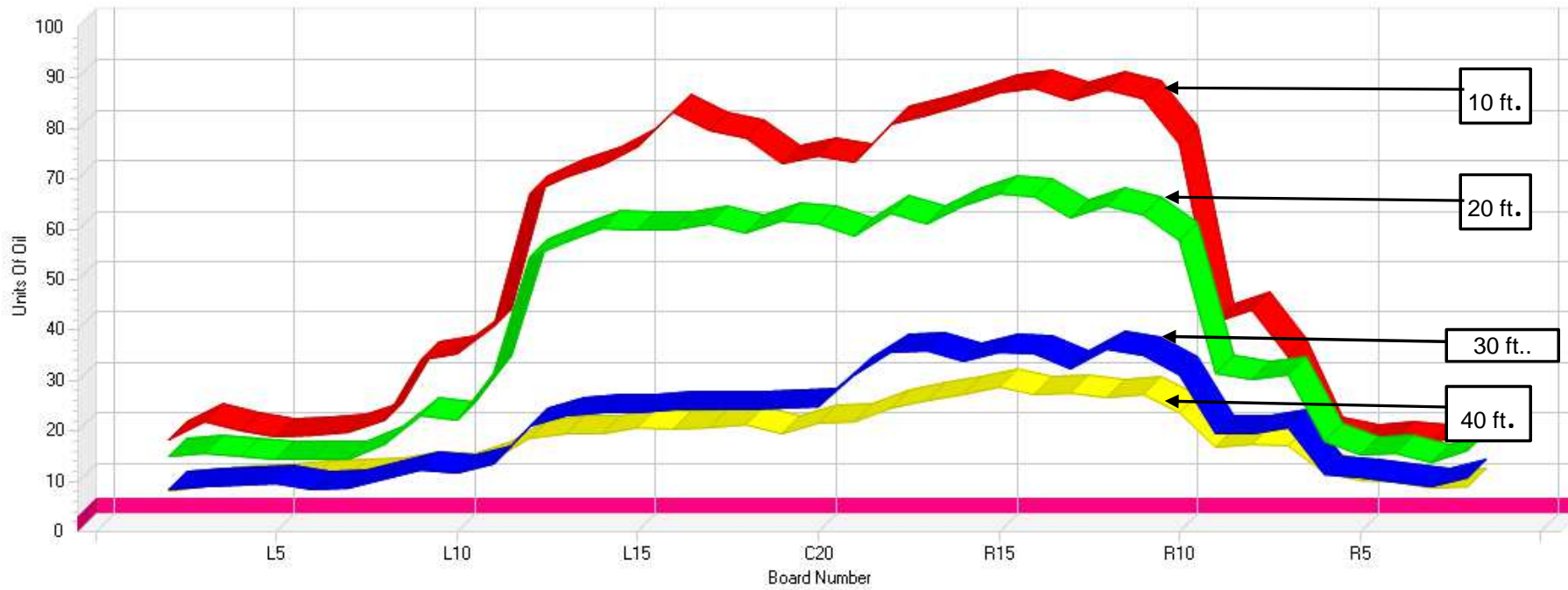


Formula ACC

HVO **SUMMIT**

Utopia
LANE
LUBRICANT

Tentative



First Tape Reading
10 Pin Side

7 Pin Side

Formula ACC

HVO **SUMMIT**

Utopia
LANE
LUBRICANT

Tentative



<p>rev Mode :</p> <p>Distance - Ft</p> <p>OIL Mode :</p> <p>Distances - Ft</p> <p>left to left :</p> <p>left to back :</p> <p>right to left :</p> <p>right to back :</p> <p>right to right :</p> <p>Transfer Rate %</p> <p>SPEED SETTINGS:</p> <p>Trail</p> <p>Condition</p> <p>Stop</p>	<table border="1"> <tr><th colspan="2">Pass 1</th></tr> <tr><td colspan="2">Double</td></tr> <tr><td>Forward</td><td>Reverse</td></tr> <tr><td>41.0</td><td>41.2</td></tr> </table> <table border="1"> <tr><th colspan="2">Pass 2</th></tr> <tr><td colspan="2">Double</td></tr> <tr><td>Forward</td><td>Reverse</td></tr> <tr><td>21.0</td><td>25.0</td></tr> </table> <table border="1"> <tr><th colspan="2">Pass 1</th></tr> <tr><td colspan="2">Double</td></tr> <tr><td>Forward</td><td>Reverse</td></tr> <tr><td>18.0</td><td>0.0</td></tr> <tr><td>22.0</td><td>18.0</td></tr> <tr><td>16.0</td><td>26.0</td></tr> <tr><td>33.0</td><td>36.0</td></tr> <tr><td>25.0</td><td>18.0</td></tr> <tr><td>18.0</td><td>0.0</td></tr> <tr><td>28</td><td>55</td></tr> </table> <table border="1"> <tr><th colspan="2">Pass 2</th></tr> <tr><td colspan="2">Double</td></tr> <tr><td>Forward</td><td>Reverse</td></tr> <tr><td>1.0</td><td>0.0</td></tr> <tr><td>4.0</td><td>0.0</td></tr> <tr><td>17.0</td><td>16.0</td></tr> <tr><td>20.0</td><td>24.0</td></tr> <tr><td>7.0</td><td>8.0</td></tr> <tr><td>1.0</td><td>0.0</td></tr> <tr><td>100</td><td>85</td></tr> </table>	Pass 1		Double		Forward	Reverse	41.0	41.2	Pass 2		Double		Forward	Reverse	21.0	25.0	Pass 1		Double		Forward	Reverse	18.0	0.0	22.0	18.0	16.0	26.0	33.0	36.0	25.0	18.0	18.0	0.0	28	55	Pass 2		Double		Forward	Reverse	1.0	0.0	4.0	0.0	17.0	16.0	20.0	24.0	7.0	8.0	1.0	0.0	100	85	<p>Start/Fin Mode <input type="checkbox"/> Off</p> <p>Trail-Mode Distance <input type="text" value="0.0"/> Ft</p> <p>Shipping mode <input type="checkbox"/> Full</p> <p>Start <input type="text" value="0.0"/> Ft</p> <p>Cleaner Pad Distance <input type="text" value="61.0"/> Ft</p> <p>Vacuum <input type="checkbox"/> On Start</p> <p>Cleaner Flow to oil <input type="text" value="100"/> %</p> <p>Back base <input type="text" value="80"/> %</p>
Pass 1																																																										
Double																																																										
Forward	Reverse																																																									
41.0	41.2																																																									
Pass 2																																																										
Double																																																										
Forward	Reverse																																																									
21.0	25.0																																																									
Pass 1																																																										
Double																																																										
Forward	Reverse																																																									
18.0	0.0																																																									
22.0	18.0																																																									
16.0	26.0																																																									
33.0	36.0																																																									
25.0	18.0																																																									
18.0	0.0																																																									
28	55																																																									
Pass 2																																																										
Double																																																										
Forward	Reverse																																																									
1.0	0.0																																																									
4.0	0.0																																																									
17.0	16.0																																																									
20.0	24.0																																																									
7.0	8.0																																																									
1.0	0.0																																																									
100	85																																																									

